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Outline:

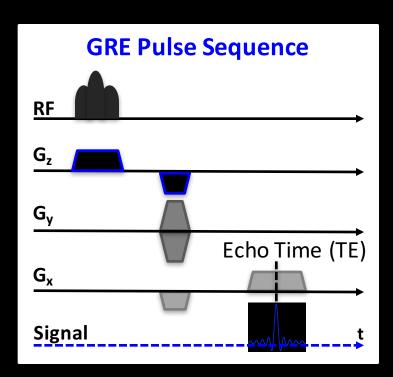
- Why QSM acquisition is slow
- Parallel imaging
- Efficient trajectories
- Exploit unused sequence time
- Multi-orientation sampling: COSMOS and STI

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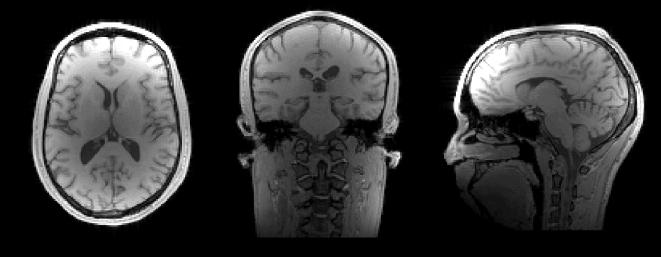
QSM Data Acquisition

- Basic GRE pulse sequence:
 - Readout pre-phasing gradient dephases spins
 - They are rephased using a readout gradient with opposite polarity
 - Peak signal occurs at Echo Time (TE)
 - Same module is repeated at Repetition Time (TR)



3D-GRE is Actually Fast

- 3D-GRE excites the whole imaging volume
- Collects one line of k-space per TR using the basic GRE module

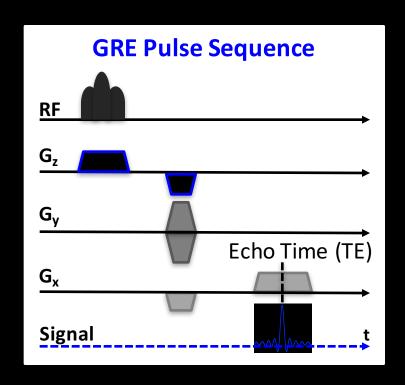


1.5 mm iso $160 \times 160 \times 128 \text{ mtx}$ $\Rightarrow 160 \times 128 \text{ TR's}$

TE = 3 ms, TR = 5 ms \Rightarrow 1:40 min acquisition

TE for Optimal Phase SNR

- Since transverse signal decays due to T2*, shortest TE gives optimal magnitude SNR
- But phase evolves linearly with time, favoring long TE
- Phase SNR depends on transverse magnetization, T2* decay rate, and TE



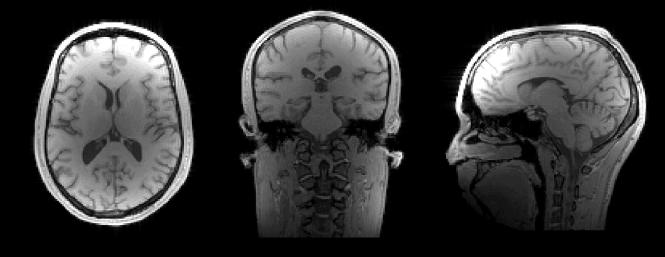
$$TE_{optimal} = T2*$$

Take
$$TE_{optimal} = 40 \text{ ms}$$

Necessitate long TR => lengthy scan

3D-GRE is Actually Fast

- 3D-GRE excites the whole imaging volume
- Collects one line of k-space per TR using the basic GRE module

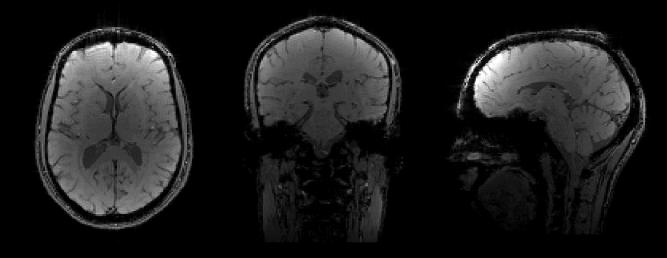


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TE = 3 ms, TR = 5 ms \Rightarrow 1:40 min acquisition

3D-GRE is Slow for QSM

- Need late TE to build up phase contrast
- But this leads to increased scan time

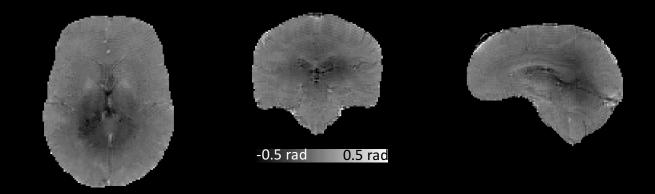


1.5 mm iso $160 \times 160 \times 128 \text{ mtx}$ $\Rightarrow 160 \times 128 \text{ TR's}$

 $TE_{optimal} = 40 \text{ ms}$, TR = 42 ms $\Rightarrow 14:20 \text{ min acquisition}$

3D-GRE is Slow for QSM

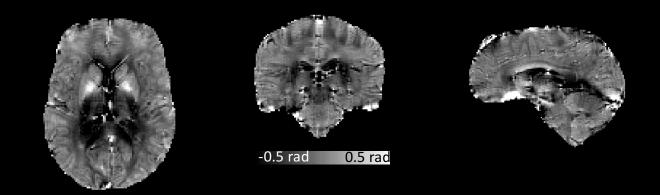
Low phase contrast at short TE:



Tissue phase @ TE = 3 ms

3D-GRE is Slow for QSM

Improved phase contrast at late TE:



Tissue phase @ TE = 19 ms

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Accelerated 3D-GRE Acquisition

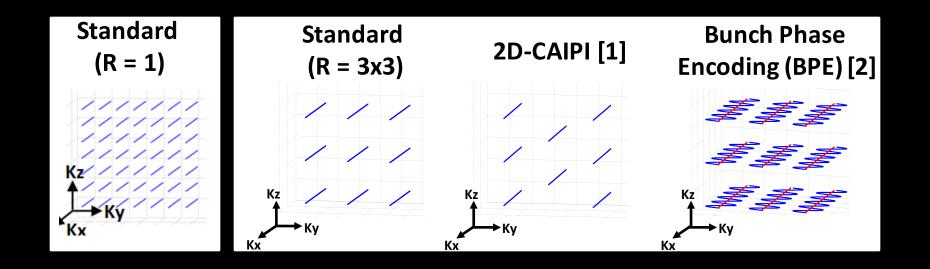
- Parallel Imaging (e.g. SENSE [1], GRAPPA [2]) uses encoding power of receiver coils to reconstruct images from undersampled k-space
- Up to 3-fold acceleration with good quality

- In Partial Fourier, one half of k-space completely filled, and small amount of data in the other half is collected
- Real signals have conjugate symmetric k-space:
 Enforce to fill up the missing half

- Combine Parallel Imaging & Partial Fourier for 4-fold accelerated 3D-GRE [3]
 - [1] KP Pruessmann et al, MRM 1999
 - [2] MA Griswold et al, MRM 2002
 - [3] AP Fan et al, MRM 2014

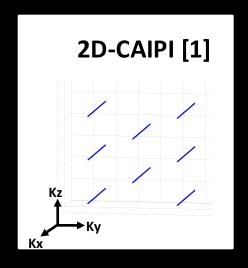
Highly Accelerated 3D-GRE

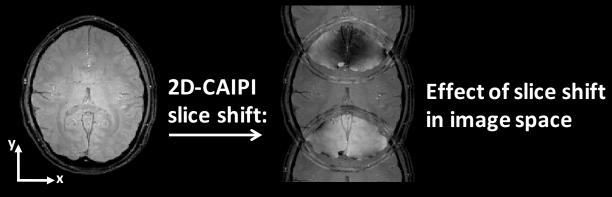
For higher acceleration, undersample both in Ky and Kz phase encoding



Highly Accelerated 3D-GRE: 2D-CAIPI

 2D Controlled Aliasing in Parallel Imaging (CAIPI) samples data in a honeycomb pattern [1]

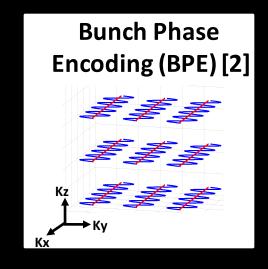


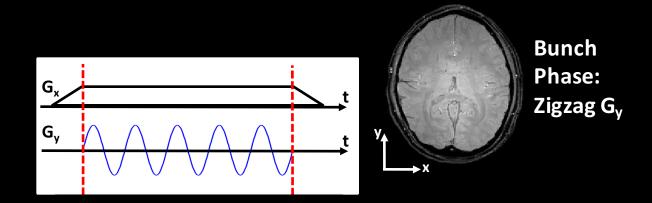


[1] FA Breuer et al, MRM 2006

Highly Accelerated 3D-GRE: Bunch Encoding

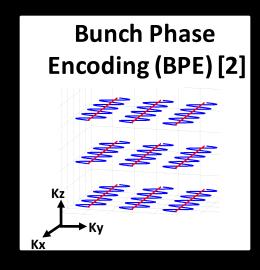
 Bunch Encoding plays a sinusoidal gradient during readout to spread voxels along readout direction [2]

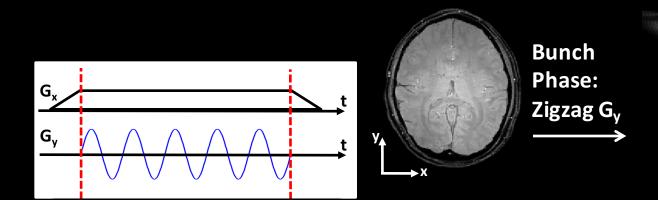


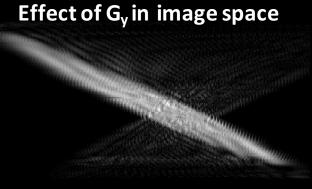


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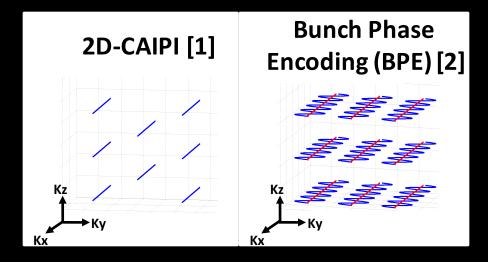




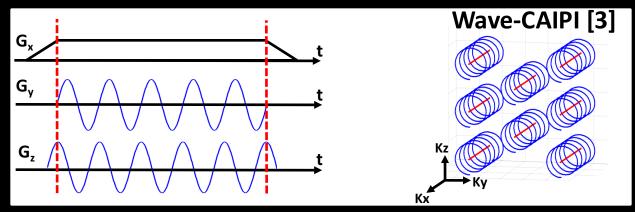


Highly Accelerated 3D-GRE: Wave-CAIPI

 Wave-CAIPI combines 2D-CAIPI honeycomb sampling with Bunch Encoding in both Gy and Gz axes [3]



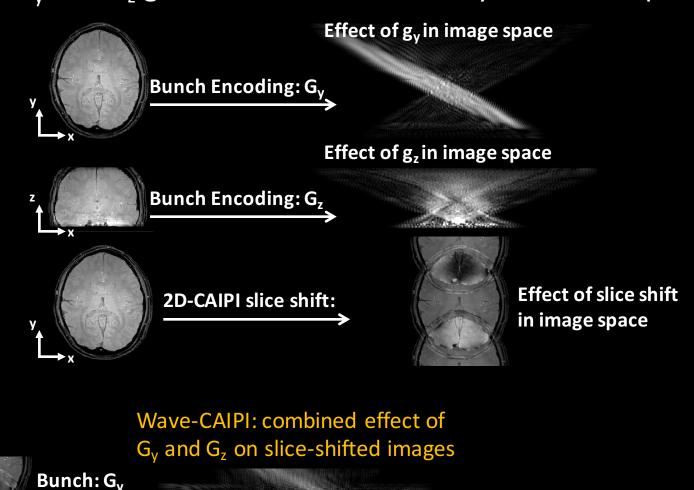
Spread aliasing in 3D to take full advantage of 3D coil profiles



[1] FA Breuer et al, MRM 2006 [2] H Moriguchi et al, MRM 2006 [3] B Bilgic et al, MRM 2015

Wave-CAIPI spreads voxels in 3 dimensions

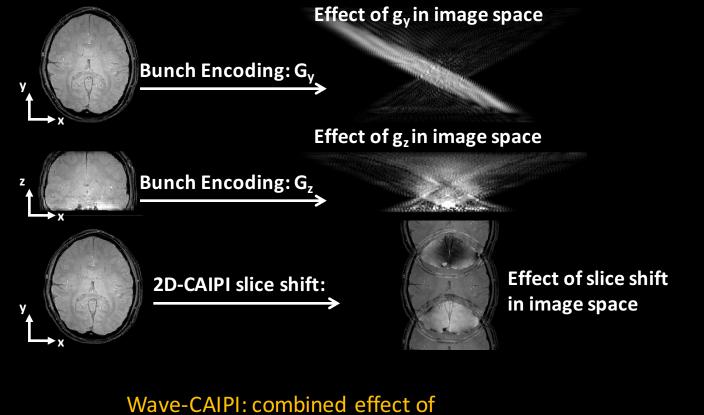
Combination of G_v and G_z gradients with slice shifts yields voxel spreading across 3D

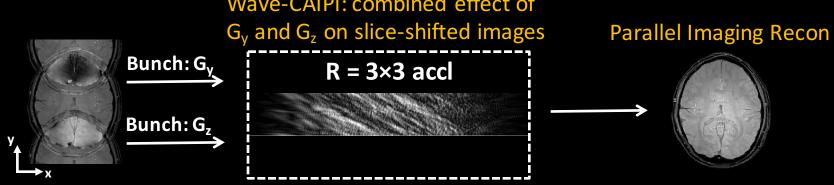


Bunch: G_z

Wave-CAIPI spreads voxels in 3 dimensions

Combination of G_v and G_z gradients with slice shifts yields voxel spreading across 3D

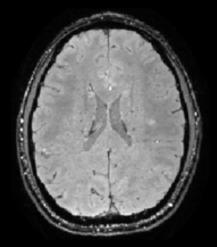


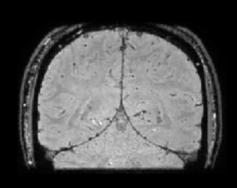


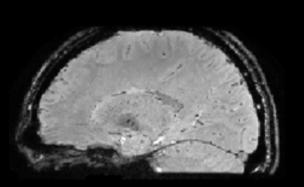
Automated Estimation of Wave-Caipi Trajectory

- Theoretical trajectory does not match the actual trajectory played on the gradients
- Since these are sinusoidal waveforms, just need to estimate amplitude and delay
- Trajectory coefficients and image content can be jointly estimated from undersampled data [1]

Wave-CAIPI: Dual Echo w/ flow comp, 1mm iso in 1min 51s

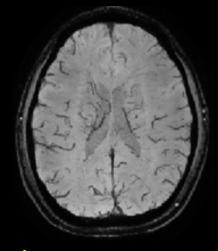






 $R=3\times3$ accl, $TE = \{15,32\}$ ms

SWI MIP



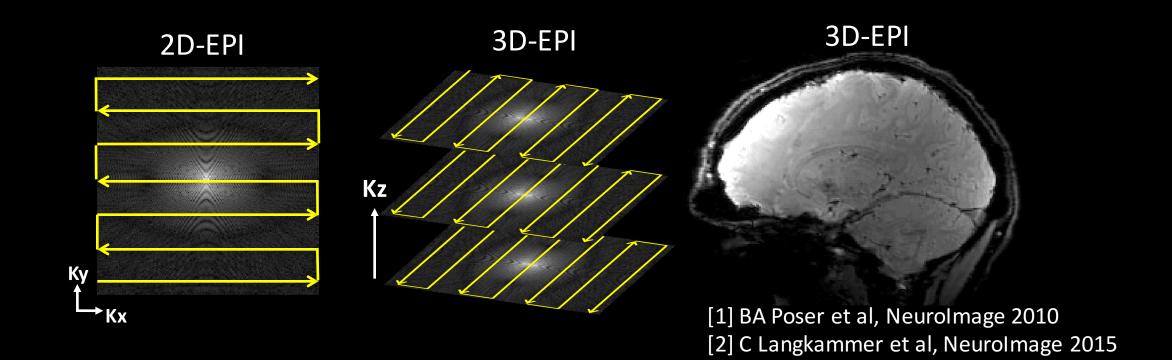
Online Recon: 2 min

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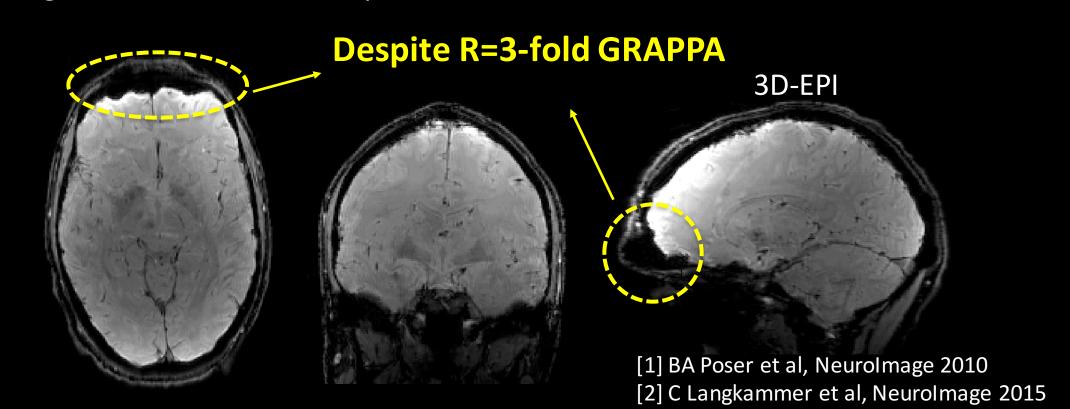
3D-EPI Acquisition

- 2D Echo Planar Imaging (EPI) collects the entire Kx-Ky plane per RF excitation
- This makes EPI very efficient for rapid imaging
- EPI can be extended to 3D imaging with phase encoding in Kz
- 3D-EPI is extremely fast [1,2]:
 1 mm iso whole brain in 30 seconds



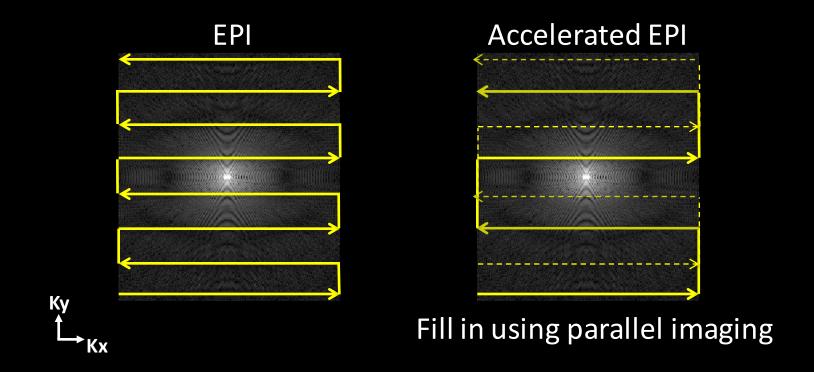
3D-EPI Acquisition

- 3D-EPI is extremely fast [1,2]:
 1 mm iso whole brain in 30 seconds
- A drawback of EPI is the distortion in phase encoding direction
- Can be mitigated with:
 - Parallel imaging
 - Segmented / multi-shot acquisition



Highly Accelerated 3D-EPI

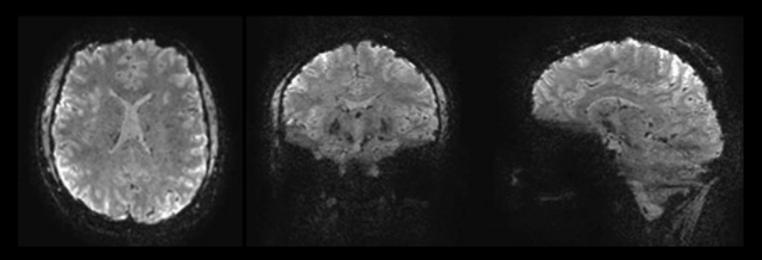
 Distortion in 3D-EPI can be reduced by high in-plane acceleration, thus shortening echo spacing



Highly Accelerated 3D-EPI

 Distortion in 3D-EPI can be reduced by high in-plane acceleration, thus shortening echo spacing

0.8 mm iso whole brain in 7.3 sec @ 3T

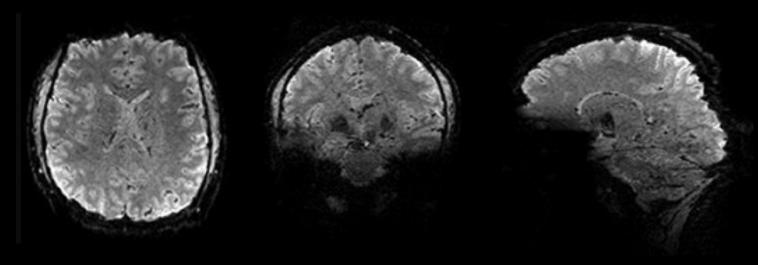


16-fold in-plane (Ky) acceleration using 2D-CAIPI [1,2]

Highly Accelerated 3D-EPI

- Distortion in 3D-EPI can be reduced by high in-plane acceleration, thus shortening echo spacing
- Total acceleration can be distributed between Ky-Kz to trade speed for distortion

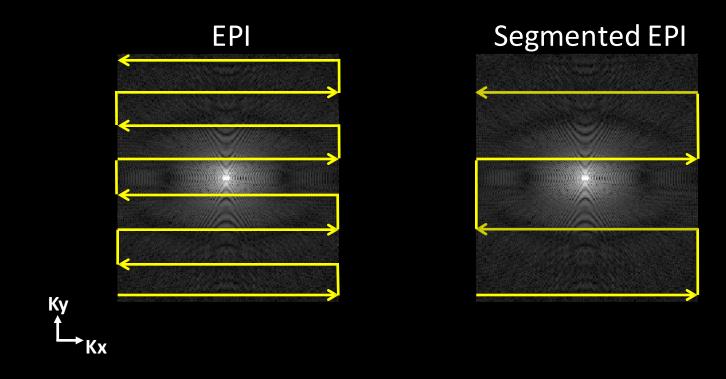
0.8 mm iso whole brain in 2.0 sec @ 3T



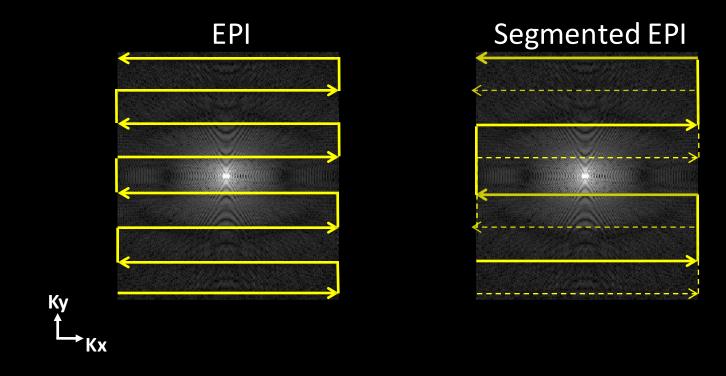
4-fold in-plane (Ky) acceleration
4-fold Kz acceleration using 2D-CAIPI [1,2]

[1] BA Poser et al, ISMRM 2014 [2] M Narsude et al, MRM 2016

 Distortion in 3D-EPI can be reduced by acquiring data in multiple segments, thus shortening echo spacing

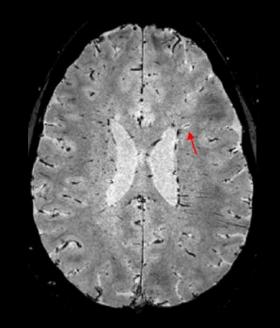


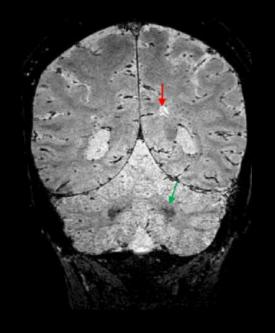
 Distortion in 3D-EPI can be reduced by acquiring data in multiple segments, thus shortening echo spacing

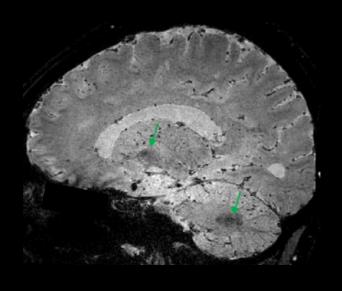


- Distortion in 3D-EPI can be reduced by acquiring data in multiple segments, thus shortening echo spacing
- Allows high resolution 3D-EPI with low distortion [1]
- At the expense of some reduction in efficiency

0.55 mm iso whole brain in 4 min @ 3T



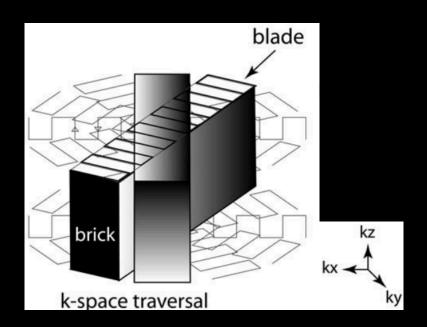


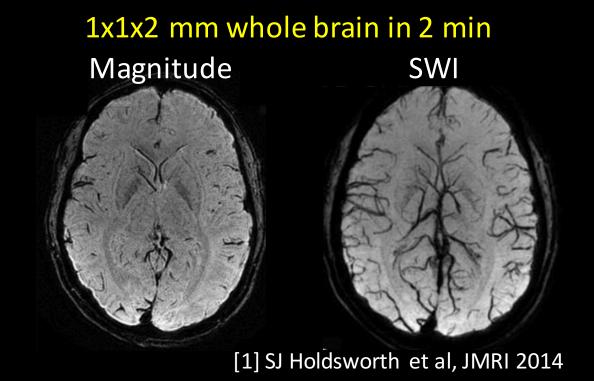


- Distortion in 3D-EPI can be reduced by acquiring data in multiple segments, thus shortening echo spacing
- Another way is 3D Propeller-EPI, where blades of EPI segments are acquired sequentially [1]:
- Distortion is reduced by a factor of N_{read} / N_{blade}

N_{read}: target readout width

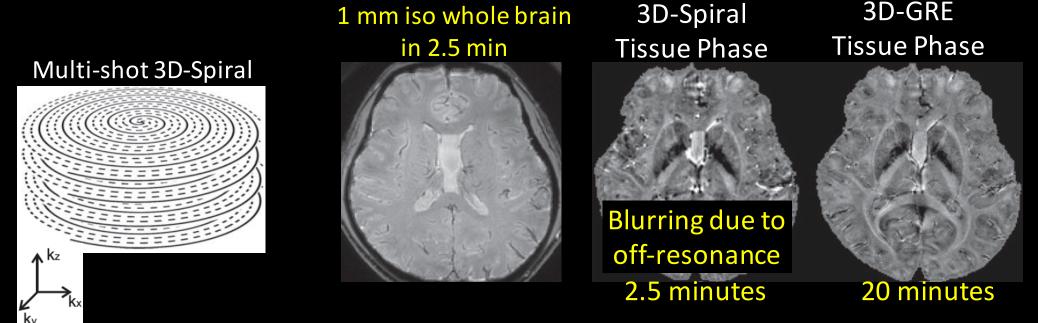
N_{blade}: blade width





3D-Spiral Acquisition

- Alternative readout strategy is the spiral trajectory, which allows rapid and efficient coverage of k-space
- It can be extended to 3D with stack-of-spirals using phase encoding along Kz [1]:
- Multiple shots (interleaves) are required to achieve FOV



	PROS	CONS
3D-GRE	 No distortion, only voxel shift in readout due to off-resonance Simple recon: FFT Simple Parallel Imaging 	Slow acquisition
3D-EPI	Very fastRelatively simple recon: FFTRelatively simple Parallel Imaging	Off-resonance causes distortion
3D-Spiral	Very fastNo geometric distortionSpiral-in allows TE close to TR	Difficult recon: Non-CartesianOff-resonance causes blurring
Wave-CAIPI	 Fast No distortion, only voxel shift in readout due to off-resonance Relatively simple Parallel Imaging 	Relatively slow recon

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Echo-Shift

- Long TE desired to build up phase contrast leads to long TR and acquisition time
- Echo-shift exploits unused sequence time and interleaves multiple echos within a single TR
- This improves efficiency in 2D [1] or 3D [2] acquisitions
- Echo-shift is known as PRESTO in fMRI [3], and has been combined with Simultaneous MultiSlice (SMS) [4] for highly accelerated 2D imaging

[1] CTW Moonen et al, MRM 1992

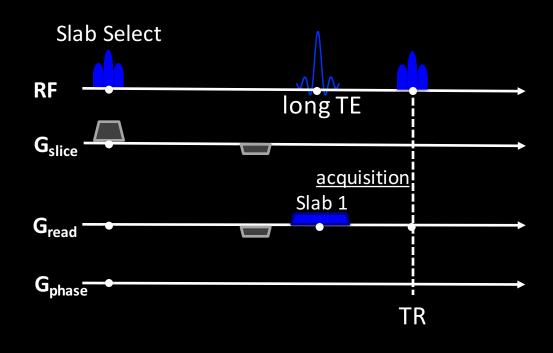
[2] YJ Ma et al, MRM 2015

[3] G Liu et al, MRM 1993

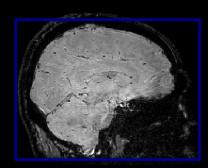
[4] R Boyacioğlu et al, MRM 2016

Conventional 3D-GRE

Conventional 3D-GRE: substantial unused time due to late TR

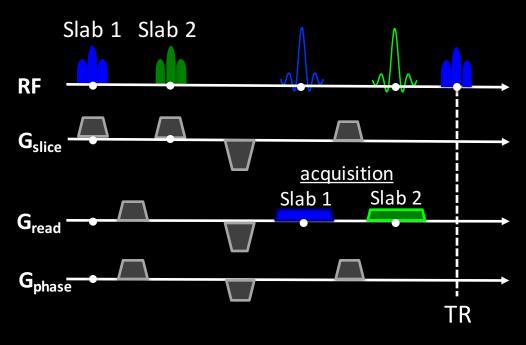


Conventional 3D encoding

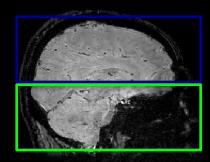


Multi-Slab Echo-Shift for 3D-GRE

Multi-Slab Echo-Shift [1]: add a second readout for faster encoding



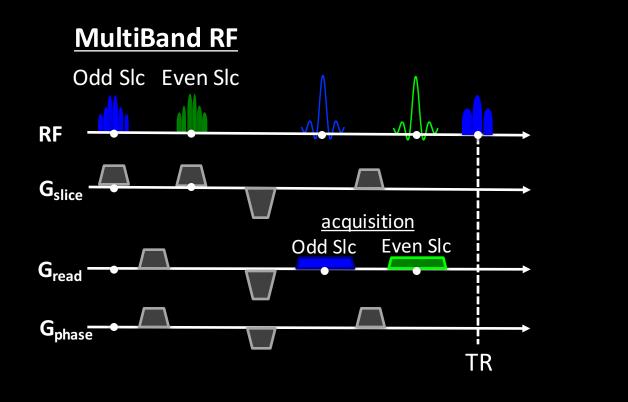
Multi-Slab Echo-Shift



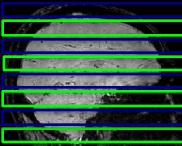
- Slab boundary artifact
- Acceleration in head-foot more difficult since distance between aliasing voxels reduced by half

Simultaneous MultiSlice Echo-Shift for 3D imaging

SMS Echo-Shift [1]: excite and encode comb slice groups

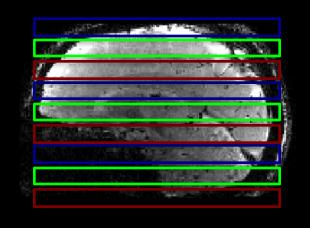


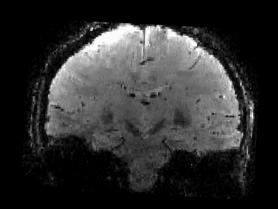


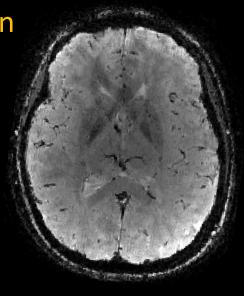


Simultaneous MultiSlice Echo-Shift for 3D imaging

3-fold Echo-Shift Acceleration

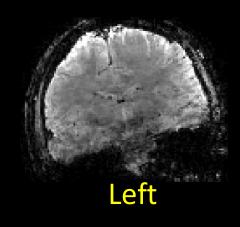


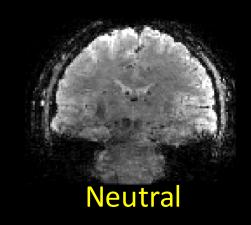


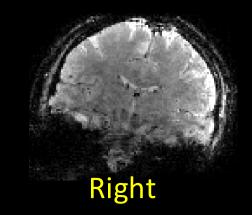


- 1×1×1.5mm³ in 5min 45s
- Long TE_{eff} = 40ms
- Combine with parallel imaging or efficient trajectories for further speed-up

Echo-Shift CS-Wave with R=15×2 acceleration

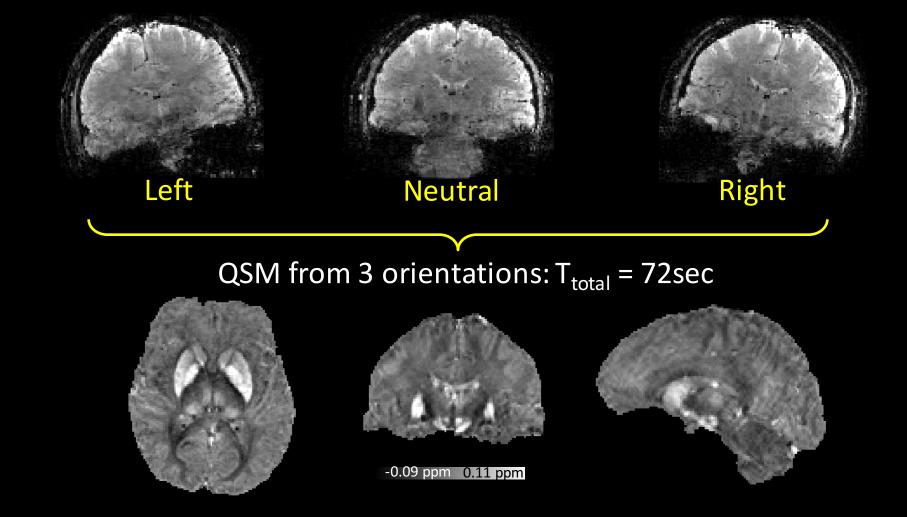






- 2-fold Echo-Shift with 15-fold Compressed Sensing Wave acceleration [1]
- **1.5** mm iso
- Long TE = 35 ms (TR = 47 ms)
- $T_{acq} = 24 \text{ sec}$

Echo-Shift CS-Wave with R=15×2 acceleration

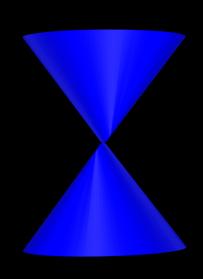


Accelerated QSM

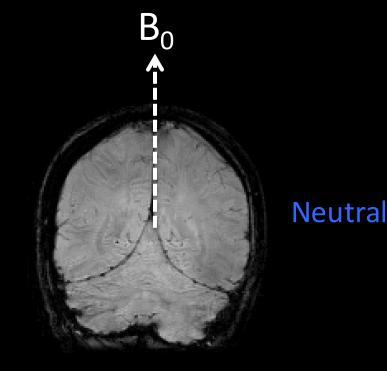
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- Susceptibility inversion is made difficult by the zeros in the susceptibility kernel D
- These zeros lie on a conical surface:

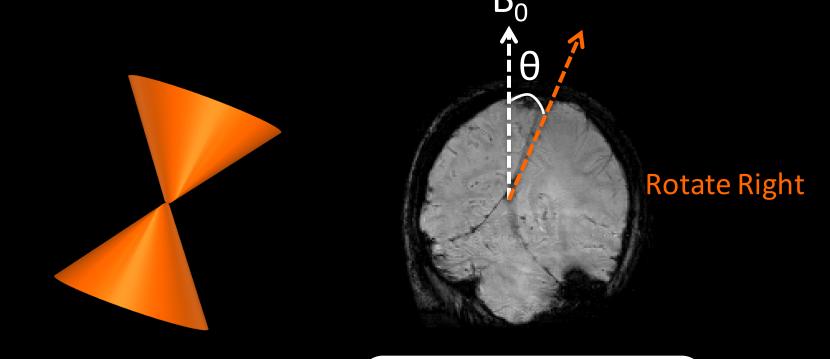


$$\delta = F^{-1}DF\chi$$



$$D = \frac{1}{3} - \frac{k_z^2}{k_x^2 + k_y^2 + k_z^2}$$

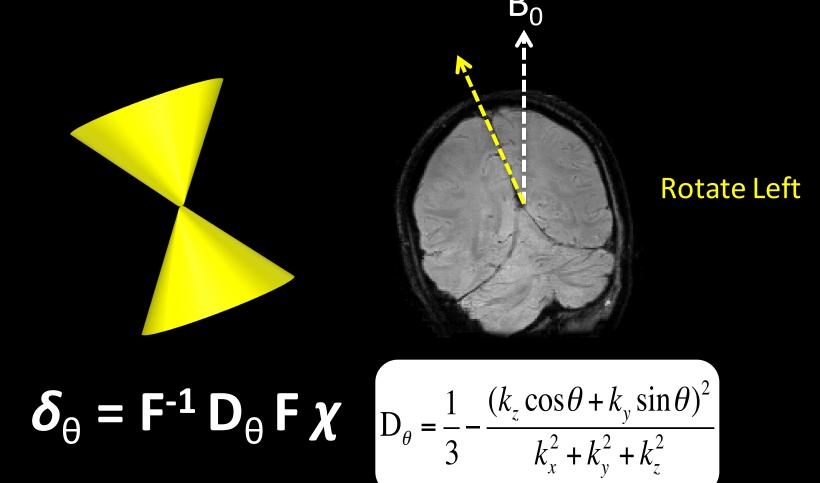
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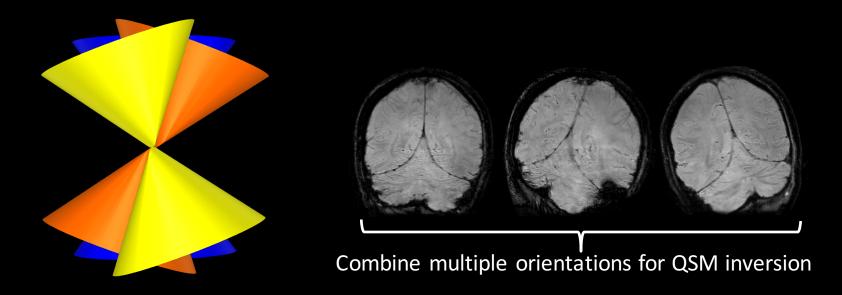
$$\delta_{\theta} = F^{-1} D_{\theta} F \chi$$

$$D_{\theta} = \frac{1}{3} - \frac{(k_z \cos \theta + k_y \sin \theta)^2}{k_x^2 + k_y^2 + k_z^2}$$

- Susceptibility inversion is made difficult by the zeros in the susceptibility kernel D
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- Susceptibility inversion is made difficult by the zeros in the susceptibility kernel D
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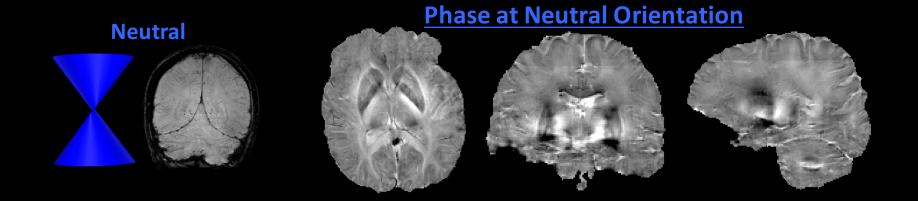


Undersampling is substantially mitigated

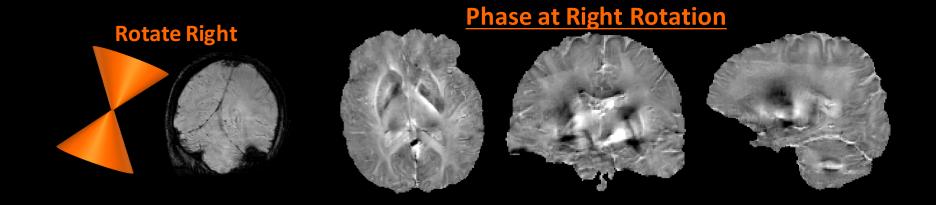
Calculation of Susceptibility Through Multiple Orientation Sampling (COSMOS) [1,2]

[1] T Liu et al, MRM 2009 [2] T Liu et al, MRM 2011

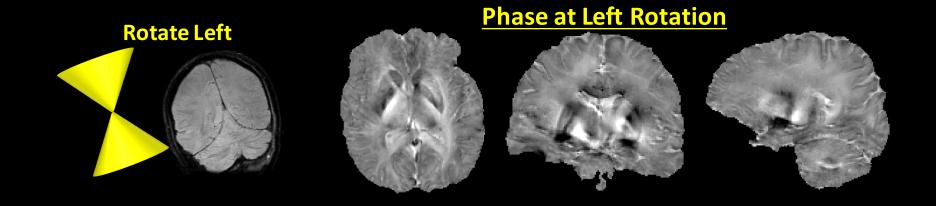
After phase processing and spatial registration:



After phase processing and spatial registration:



After phase processing and spatial registration:



COSMOS improves conditioning of the inverse problem at the expense of scan time:

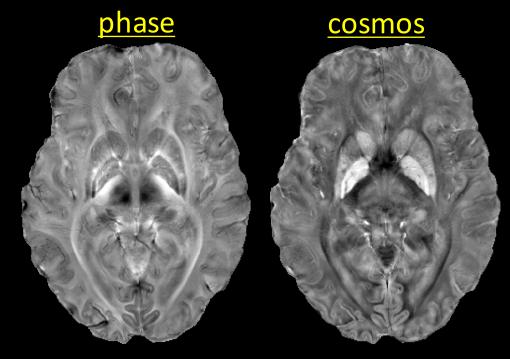
T_{acq}=14 min **COSMOS QSM from 4 orientations Wave-CAIPI** Large FOV: 240×240×192 Regularized QSM from 1-orientation $T_{acq}=3.5$ min T_{acq} =3.5 min per orientation **Streaking** artifacts

 $R = 3 \times 3$

Towards in vivo Histology with QSM

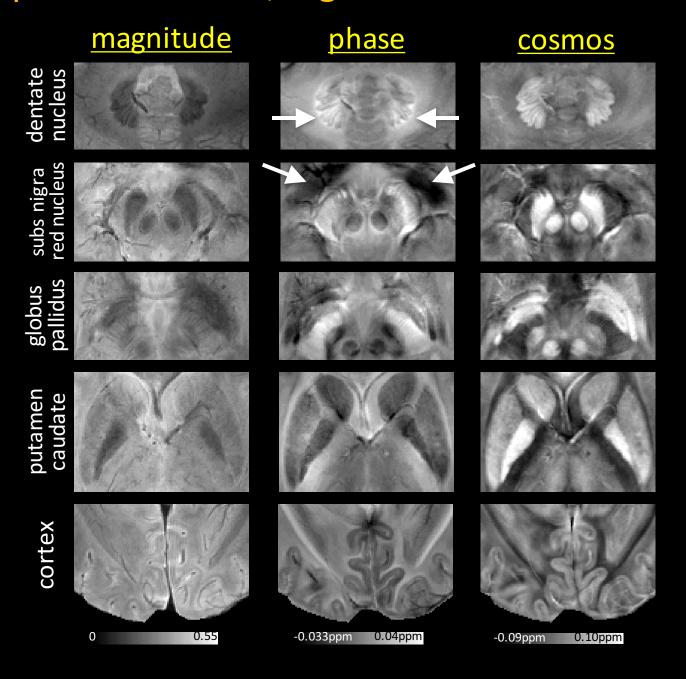
- High-resolution COSMOS at ultra high field yields superb contrast to reflect the underlying anatomy [1-3]
- High-resolution COSMOS requires > 1 hour of scanning [1-3]

- Whole-brain, high resolution COSMOS @ 7T
 - Wave-CAIPI with R=5×3 fold acceleration [4]
 - 5:35 min / rotation @ 0.5 mm iso
 - **20** min total protocol for 3-orientations



- [1] A Deistung et al, Neurolmage 2012
- [2] D Khabipova et al, NeuroImage 2015
- [3] A Deistung et al, Frontiers 2013
- [4] B Bilgic et al, NeuroImage 2016

Rapid whole-brain, high resolution COSMOS @ 7T



Susceptibility Tensor Imaging (STI)

- STI models the susceptibility in each voxel as a tensor to capture its orientation dependence [1]
- STI is more sensitive to myelin than Diffusion Anisotropy [2]
- Entails estimation of 6 unknowns in 3×3 tensor per voxel:

Requires data acquired at 6+ head orientations

- In vivo human studies necessitate very long scans at limited resolution [3,4]
- **STI acquisition takes 2 4 hours, making it impractical for in vivo human imaging**

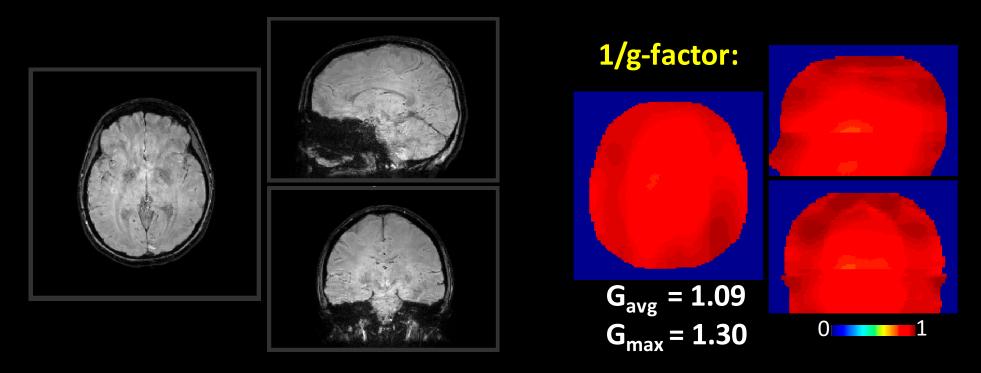
[1] C Liu, MRM 2010

[2] C Liu et al, Neurolmage 2011

[3] X Li et al, Neurolmage 2012

[4] C Wisnieff et al, NeuroImage 2013

Rapid whole-brain STI @ 3T



- Wave-CAIPI at R=5×3 fold acceleration [1]
- 90 sec / rotation @ 1.1 mm iso
- 30 min total protocol for 12-orientations

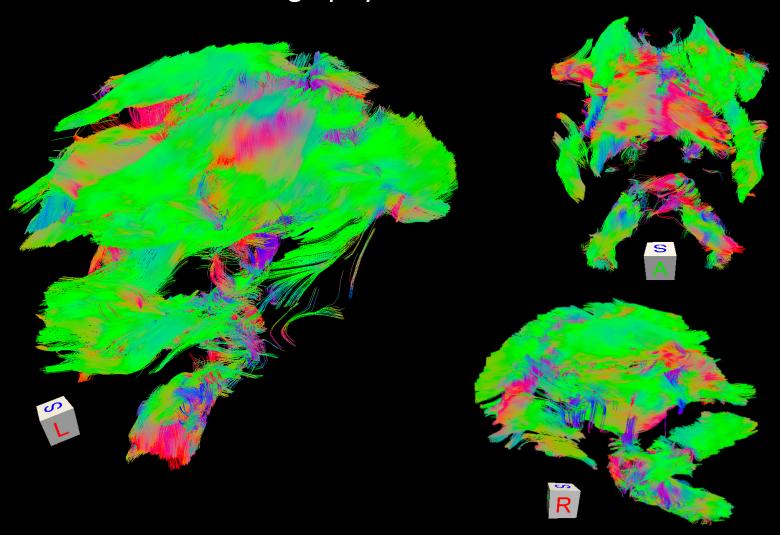
(including shimming, sensitivity calibration per orientation)

Rapid whole-brain STI @ 3T

STI Eigenvalues -0.17ppm 0.17ppm

Rapid whole-brain STI @ 3T

STI Tractography from 12 Orientations



Thanks!

Questions / Comments:

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